

Numerical Algorithms

Winter 2023/24 Prof. Dr. Carsten Burstedde Hannes Brandt



Exercise Sheet 14.

Exercise 1. (Recap IV - CG Method)

Consider the conjugate gradient and the preconditioned conjugate gradient method as introduced in the lecture.

- a) Propose two different stopping criteria for the CG method. The criteria should be scaling invariant, so scaling the entire system of linear equations by a constant $0 < \alpha \in \mathbb{R}$ should not affect the total number of iterations. How can both stopping criteria be adapted to the PCG method?
- b) For the search directions \mathbf{p}_i and the residuals \mathbf{z}_i of the PCG method prove

$$\operatorname{span}{\mathbf{p}_0,\ldots,\mathbf{p}_k} = \operatorname{span}{\mathbf{z}_0,\ldots,\mathbf{z}_k}$$

for k less or equal the total amount of iterations.

(0 Points)

Exercise 2. (Recap V - Tensor Basis)

For one-dimensional functions $\psi_i\colon [-1,1]\to\mathbb{R}$ we define a two-dimensional tensor basis of functions

$$\psi_{ij}(x,y) \coloneqq \psi_i(x)\psi_j(y)$$

on the reference element with domain $[-1, 1]^2$. Reduce the computation of the elementlocal stiffness matrix A with

$$A_{ij,kl} = \int_{-1}^{1} \int_{-1}^{1} \nabla \varphi_{ij}(x,y) \nabla \varphi_{kl}(x,y) dx dy$$

to the computation of one-dimensional integrals.

(0 Points)

Exercise 3. (Recap VI - Element Stiffness Matrix)

To solve the Poisson equation on $\Omega = (0, N) \times (0, N)$ with $N \in \mathbb{N}$ we partition $\overline{\Omega}$ into a regular $N \times N$ grid of squares. As a basis we use the bilinear 'hat functions' ϕ_{ij} that are 1 on node/corner (i, j) of the grid and 0 on every other node/corner. The element-local stiffness matrix of a cell has the form

$$\begin{pmatrix} \alpha & \beta & \gamma & \beta \\ \beta & \alpha & \beta & \gamma \\ \gamma & \beta & \alpha & \beta \\ \beta & \gamma & \beta & \alpha \end{pmatrix}$$

with $\alpha + 2\beta + \gamma = 0$.

The non-zero entries of the global stiffness matrix for a basis function ϕ_{ij} can be given in the form of a 3×3 matrix

$$\begin{pmatrix} \bar{a}_{i-1,j-1} & \bar{a}_{i-1,j} & \bar{a}_{i-1,j+1} \\ \bar{a}_{i,j-1} & \bar{a}_{i,j} & \bar{a}_{i,j+1} \\ \bar{a}_{i+1,j-1} & \bar{a}_{i+1,j} & \bar{a}_{i+1,j+1} \end{pmatrix} = \frac{1}{3} \begin{pmatrix} -1 & -1 & -1 \\ -1 & 8 & -1 \\ -1 & -1 & -1 \end{pmatrix}$$

with $\bar{a}_{kl} = A_{kl,ij}$, like in exercise 1b) of sheet 9.

- a) What is the intuition behind the equation $\alpha + 2\beta + \gamma = 0$?
- b) Deduce the values α , β and γ from the given non-zero entries of the global stiffness matrix.
- c) Instead of the weak formulation of the Poisson Equation now consider the bilinear form

$$a(u,v) \coloneqq \int_{\Omega} \nabla u^T \begin{pmatrix} c & 0 \\ 0 & d \end{pmatrix} \nabla v$$

with $c, d \in \mathbb{R}_+$. How can the α, β, γ representation of the element-local stiffness matrix be adapted to this change?

(0 Points)